





Distributed TensorFlow: A performance evaluation

End-of-internship Seminar

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https://github.com/e-bug/distributed-tensorflow-benchmarks

Introduction

What is TensorFlow?

Google's open-source software library for Machine Learning

- Best-supported client language: Python
- Experimental interfaces for: C++, Java and Go

Why TensorFlow?

- Portable & flexible \rightarrow popular in industries and in research communities
- Most CSCS clients choose TensorFlow as their Deep Learning library

Why distributed training?

Training a neural network can take an impractically long time on a single machine (even with a GPU)

Results

On 64 GPUs: ~80% scalability efficiency in Piz Daint & almost 90% in 8 8-GPU nodes





ToC

- Introduction
- TensorFlow overview
- Distributed training in TensorFlow
- Benchmarks
- Conclusion and Future Work





TensorFlow overview (1)

TensorFlow is based on data flow graphs

- Nodes represent mathematical operations
- Tensors move across the edges between nodes

Writing a TensorFlow application

- 1. Build computation graph
- 2. Run instances of that graph



Figure 1: Computational graph for regularized Multiclass SVM loss (CS231N, Stanford University)





TensorFlow overview (2)



Example: Linear Regression in TensorFlow

Figure 2: Computational graph for Linear Regression with squared loss

import matplotlib.pyplot **as** plt **import** numpy **as** np **import** tensorflow **as** tf

# =====================================		==== #
#	LOAD DATA	#
# =====================================		==== #
# Generate some data as y=3*x + noise		
N_SAMPLES = 10		
x_in = np.arange(N_SAMPLES)		
y in = 3×10^{-1} in + np.random.randn(N SAMPLES)		
data = list(zip(x in, y in))	,	





TensorFlow overview (3)



Example: Linear Regression in TensorFlow

```
Figure 2: Computational graph for Linear Regression with squared loss
```

Create weight and bias, initialized to 0
w = tf.Variable(0.0, name='weight')
b = tf.Variable(0.0, name='bias')

Build model to predict y
y_predicted = x * w + b

Use the square error as the loss function loss = tf.square(y - y_predicted, name='loss')

```
# Use gradient descent to minimize loss
optimizer = tf.train.GradientDescentOptimizer(0.001)
train = optimizer.minimize(loss)
```





#

TensorFlow overview (4)



Example: Linear Regression in TensorFlow

Figure 2: Computational graph for Linear Regression with squared loss



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TensorFlow overview (5)



Example: Linear Regression in TensorFlow

Figure 2: Computational graph for Linear Regression with squared loss





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Distributed training in TensorFlow (1)

- Split the training of a neural network across multiple nodes
- Most common approach: data parallelism
 - Each node has an instance of the model and reads different training samples
 - Also known as "between-graph replication" in TensorFlow
- Processes can either be:
 - Worker
 - Runs the model
 - Sends its local gradients to the PSs
 - Receives updated variables back
 - Parameter Server (PS)
 - Hosts trainable variables
 - Updates them with values sent by the Workers
- PSs sum gradients to merge in one step what each Worker has learned to reduce the loss







Distributed training in TensorFlow (2)

- Workers need to send their updates to the correct Parameter Servers
 - Use TensorFlow's replica_device_setter for a deterministic variable allocation
- Parameter Servers and Workers may coexist on the same machine
 - Recommended when Workers run on GPUs
 - Reduce the number of nodes
 - Minimize network communications







Distributed training in TensorFlow (3)

- Define cluster of nodes and the role of each of them (PS/Worker)
- The following code snippet (<u>https://clindatsci.com/blog/2017/5/31/distributed-tensorflow</u>) would be executed on each machine in the cluster, but with different arguments

import sys **import** tensorflow **as** tf

```
# Specify the cluster's architecture
cluster = tf.train.ClusterSpec(
{'ps': ['192.168.1.1:1111'],
'worker': ['192.168.1.2:1111','192.168.1.3:1111']})
```

Train your model here

csc:



Distributed training in TensorFlow (4)

Running distributed TensorFlow on Piz Daint

- Write a Python script (TF_SCRIPT) accepting job_name, task_index, ps_hosts and worker_hosts TensorFlow flags
- Write a Bash script like the following one; run_dist_tf_daint.sh will specify the cluster from allocated nodes #!/bin/bash # set TensorFlow script parameters

#SBATCH --job-name=distributed tf #SBATCH --time=00:12:00 #SBATCH --nodes=8 #SBATCH --constraint=gpu #SBATCH -- output=distributed tf.%j.log

Arguments:

\$1: TF NUM PS: number of parameter servers # \$2: TF NUM WORKER: number of workers

load modules module load daint-gpu module load TensorFlow **export TF_SCRIPT="\$HOME**/project_dir/project_script.py"

```
export TF FLAGS="--num gpus=1 --batch size=64
                 --num batches=4 --data format=NCHW"
```

set TensorFlow distributed parameters export TF_NUM_PS=\$1 # 1 export TF_NUM_WORKERS=\$2 # \$SLURM JOB NUM NODES # export TF WORKER PER NODE=1 # export TF PS PER NODE=1 # export TF PS IN WORKER=true

run distributed TensorFlow **DIST_TF_LAUNCHER_DIR=\$SCRATCH**/run dist tf daint dir cd \$DIST_TF_LAUNCHER_DIR ./run dist tf daint.sh





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Benchmarks (1)

- Model
 - InceptionV3
 - Neural Network for 1000-class image classification (ImageNet competition)
 - Optimized code for benchmarks available from Google
- Data set
 - ImageNet: 1,280,000 images (144 GB)
- TensorFlow 1.1.0
- Performance metric
 - Number of trained images per second







Benchmarks (2)

- Methodology
 - For each configuration of number of Workers and number of nodes
 - Run with different number of Parameter Servers on synthetic data (no I/O access)
 - Report best setting of number of Workers and number of PSs
 - Run best setting on real data (with I/O access)
 - Results repeatability
 - Run each test 5 times and average times together (Google's approach)
 - Compare results with Google's
 - Limit impact on Piz Daint (200+ tests)
 - For each test
 - 10 warmup steps
 - Next 100 steps are averaged





Benchmarks (3)

- Systems
 - Piz Daint (NVIDIA Tesla P100 1 GPU per node)
 - Amazon EC2 instances
 - p2.xlarge (NVIDIA Tesla K80 1 GPU per node)
 - p2.8xlarge (NVIDIA Tesla K80 8 GPUs per node)
- Benchmarks from Google available at <u>https://www.tensorflow.org/performance/benchmarks</u>
 - Google's systems
 - NVIDIA DGX-1 (NVIDIA Tesla P100 8 GPUs per node)
 - Amazon p2.8xlarge (NVIDIA Tesla K80 8 GPUs per node)





Benchmarks (4)

NVIDIA Tesla P100 - synthetic data (no I/O) - up to 8 GPUs



- 99.56% on 8 GPUs in NVIDIA DGX-1
- 92.07% on 8 GPUs in Piz Daint
- 8 nodes in Piz Daint have similar performance as an NVIDIA DGX-1





Benchmarks (5)



NVIDIA Tesla K80 - synthetic data (no I/O) - up to 8 GPUs

- 94.58% and 94.44% on 8 GPUs in p2.8xlarge
- 93.45% on 8 GPUs in p2.xlarge
- Up to 8 GPUs, compute bound application





Benchmarks (6)

NVIDIA Tesla K80 - synthetic data (no I/O) - up to 64 GPUs



- 92.86% and 88.55% on 64 GPUs in p2.8xlarge
- 50.96% on 64 GPUs in p2.xlarge
- Intuition: inter-node network capacity reached with 64 GPUs in p2.xlarge





Benchmarks (7)

Piz Daint (NVIDIA Tesla P100) - synthetic and real data - up to 128 GPUs



- 80.46% (synthetic) and 72.39% (real) on 64 GPUs
- 52.11% (synthetic) and 51.63% (real) on 128 GPUs
- Intuition: inter-node network capacity reached with 128 nodes





Benchmarks (8)

p2.xlarge (NVIDIA Tesla K80) - synthetic and real data - up to 128 GPUs



Scalability efficiency (local SSD on each node)

- 50.96% (synthetic) and 51.33% (real) on 64 GPUs
- 27.56% (synthetic) and 28.09% (real) on 128 GPUs
- Intuition: inter-node network capacity reached with 64 nodes





Benchmarks (9)

p2.8xlarge (8 * NVIDIA Tesla K80) - synthetic and real data - up to 128 GPUs



Scalability efficiency (local SSD on each node)

- 88.55% (synthetic) and 74.39% (real) on 64 GPUs
- 85.24% (synthetic) and 73.67% (real) on 128 GPUs
- Intuition: inter-node network capacity not reached (only 16 nodes for 128 GPUs)





Benchmarks (9)

I/O overhead



- ~17% on p2.8xlarge when 8 GPUs per node are used
- ~1% on p2.xlarge
- ~11% on Piz Daint when 8 to 64 GPUs used, ~1.5% otherwise





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Conclusion

- 8 nodes in Piz Daint have similar performance to 1 NVIDIA DGX-1
- Scalability for InceptionV3 in TensorFlow
 - On Piz Daint
 - Supposedly inter-node bandwidth capacity reached after 64 nodes
 - I/O cost ~11%
 - On a multi-GPU system
 - Inter-node traffic algorithmically reduced by the number of GPUs per node (interconnect seems to have no real impact)
 - Using local SSDs and 8 GPUs per node adds a constant ~17% I/O overhead (PCIe traffic)
 - No benchmarks available for multiple NVIDIA DGX-1
 - ⇒ Estimation according to the examined use case: Similar performance between 64 nodes on Piz Daint and 8 NVIDIA DGX-1 connected by a reasonable inter-node network

Future Work

- Investigate impact of training accuracy in distributed setting (preliminary results)
- Profile TensorFlow communication patterns
- Analyze influence of number of PSs for single- and multi-GPU systems





Conclusion

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Thank you





Backup slides

Distributed training in TensorFlow (5)

Round-robin variables







Greedy load balancing variables







replica_device_setter provides two load balancing strategies

- Round-robin (default)
- Greedy load balancing



